## Lecture 4: Equisingularity and ICIS

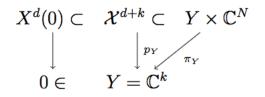
by Terence Gaffney

- Welcome to Equisingularity!
- Please read the notes for lecture 4. They will be used in the course on Determinantal singularities.
- Please do all the exercises in the notes. Whenever you are trying to understand a definition, make up an easy problem and solve it, if there isn't one already. We will have an exercise session next week.
- I encourage you to talk to me at any time during the school if you have any questions.

## I Introduction and Some Basic Examples

- ► To understand a singularity X we want to understand the "nearby" singularities—the singularities that appear in the deformations of X.
- Given a family of sets or maps, when are all the members the same?
- When are some of the members different?
- **Equisingularity** is the study of these questions.
- Advantage: Easier to say when all the members of family are the same, than when two individual sets or two maps are the same.
- Often the change in a single invariant suffices to pick out the members which different than the rest.
- Infinitesimal methods natural and powerful for the study of families.
- ► Invariants of ICIS have both a topological/ geometric and infinitesimal character. Hypersurface case: µ(f) is the TR<sub>e</sub>(f) codimension and the rank of the middle homology of the Milnor fiber of f.

## Notation



The parameter space is Y, X<sup>d</sup>(0) denotes the fiber of the family over {0}.

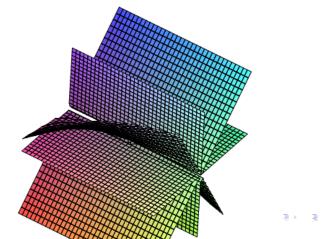
- X<sup>d+k</sup> denotes the total space of the family which is contained in Y × C<sup>N</sup>. We always assume X<sup>d+k</sup> is equidimensional with equidimensional fibers.
- We usually assume  $Y \subset \mathcal{X}^{d+k}$ ,
- $\mathcal{X} = F^{-1}(0), X(y) = f_y^{-1}(0), \text{ where } f_y(z) = F(y, z)$
- S(X) the singular locus of X.

## Definitions and Examples

- ► The family is smoothly trivial if there exists a smooth family of origin preserving bi-holomorphic germs r<sub>y</sub> such that r<sub>y</sub>(X(0)) = X(y).
- If the map-germs are only homeomorphisms we say the family is C<sup>0</sup> trivial.
- ► **Example:** Let  $\mathcal{X}$  be the family of two moving lines in the plane with equation  $F(y, z_1, z_2) = z_1(z_2 yz_1) = 0$ .
- y is the parameter, the z₂ axis is fixed, a component of every member of the family while the line z₂ − yz₁ = 0 moves with y.
- Our intuition says that all of these sets are the "same".
- In fact, the family of functions F(y, z₁, z₂) = z₁(z₂ yz₁) are all right equivalent to f₀(z₁, z₂) = z₁z₂, because they are all Morse functions. Hence the family is smoothly trivial.
- Problem: Show that for y ≠ −1 the family of functions F(y, z<sub>1</sub>, z<sub>2</sub>) = z<sub>1</sub>z<sub>2</sub>(z<sub>1</sub> − (1 + y)z<sub>2</sub>) is smoothly trivial: this shows that the family of 3 moving lines in C<sup>2</sup> is smoothly trivial.

## 4 Moving Lines

- our intuition suggests that the family of n moving distinct lines should be "equisingular". But
- ► Example: Let X be the family of four moving lines with equation F(x, y, z) = z<sub>1</sub>z<sub>2</sub>(z<sub>2</sub> + z<sub>1</sub>)(z<sub>2</sub> - (1 + y)z<sub>1</sub>) = 0. The parameter is y, the z<sub>1</sub> and z<sub>2</sub> axes and the line z<sub>2</sub> + z<sub>1</sub> = 0 are fixed.



## 4 Moving Lines continued

- **Problem:** Show that the family of 4 lines is not smoothly trivial.
- ▶ Hint: If r<sub>y</sub> is a trivialization of the family of sets, Dr<sub>y</sub>(0) must carry the tangent lines of X(0) to X(y). If a linear map preserves the lines defined by z<sub>1</sub> = 0, z<sub>2</sub> = 0, z<sub>2</sub> = -z<sub>1</sub> then the linear map must be a multiple of the identity. Hence r<sub>y</sub> can't map z<sub>2</sub> = z<sub>1</sub> to z<sub>2</sub> = (1 + y)z<sub>1</sub>, y ≠ 0.

## Goal

- The family of four lines is not smoothly trivial, but we still want to use infinitesimal methods as the foundation of our theory of equisingularity.
- The infinitesimal approach using vectorfields, promises to reduce equisingularity problems to algebra, just as Mather's work does for smooth equivalence.

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If not smooth, what kind of vectorfields do we use?

## II Rugose vectorfields and Verdier's condition W

- ► Given a family of hypersurfaces X over Y<sup>1</sup>, defined by F(y, z) consider the vectorfield:
- $V = \left(\frac{\partial}{\partial y} \xi\right)$  defined on  $\mathcal{X}_0$ ,

$$\xi(y,z) = \frac{\sum_{i=1}^{n} \frac{\partial F}{\partial y}(y,z) \overline{\frac{\partial F}{\partial z_{i}}}(y,z) \frac{\partial}{\partial z_{i}}}{\sum_{i=1}^{n} \frac{\partial F}{\partial z_{i}}(y,z) \overline{\frac{\partial F}{\partial z_{i}}}(y,z)}$$

- V well-defined and real analytic where D<sub>z</sub>(F) ≠ 0
  DF(V)(y, z) = F<sub>y</sub>(y, z) <sup>∑<sub>i=1</sub><sup>n</sup> ∂F/∂z\_i(y,z) ∂F/∂z\_i(y,z) ∂F/∂z\_i(y,z)</sup>/<sub>∑<sub>i=1</sub> ∂F/∂z\_i(y,z) ∂F/∂z\_i(y,z)</sub> = 0 where defined, which implies V tangent to X<sub>0</sub>.
- We want conditions to ensure  $\xi(y, 0) = 0$ , flow of V is at least  $C^0$ .

## Rugose vectorfields

#### Theorem

(Verdier) the vectorfield V can be integrated to give a family of homeomorphisms which trivialize  $\mathcal{X}$  provided the inequality

 $\|\xi(y,z)\| \leq C \|z\|$ 

holds on a neighborhood of the origin in  $\mathcal{X}$ , for some C > 0.

- ► Verdier called such a vectorfield a *rugose* vectorfield.
- Verdier also defined a stratification condition condition W, which ensured, that if it held between all pairs of incident strata, smooth vectorfields on the smallest stratum lifted to rugose vectorfields on larger strata.

## Condition W: Distance between linear spaces.

▶ Suppose *A*, *B* are linear subspaces at the origin in  $\mathbb{C}^N$ 

$$ext{dist}(A,B) = \sup_{\substack{u \in B^{\perp} - \{0\} \ v \in A - \{0\}}} \frac{\|(u,v)\|}{\|u\| \|v\|}.$$

Example we work with linear subspaces of ℝ<sup>3</sup>. Let A = x-axis, B ⊂ ℝ<sup>3</sup> a plane with unit normal u<sub>0</sub>, then dist(A, B) = ||u<sub>0</sub> · (1,0,0)|| = cos θ, where θ is the small angle between u<sub>0</sub> and the x-axis, in the plane they determine. So when the distance is 0, B contains the x-axis.

#### Definition

Suppose  $Y \subset \overline{X}$ , where X, Y are strata in a stratification of an analytic space, and  $\operatorname{dist}(TY_0, TX_x) \leq C\operatorname{dist}(x, Y)$  for all x close to Y. Then the pair (X, Y) satisfies **Verdier's condition** W at  $0 \in Y$  (Verdier-1976).

▶ **Theorem** The set of points of Y where (X<sub>0</sub>, Y) satisfy W is Zariski open and dense.

## W equisingular families

#### Definition

A family  $\mathcal{X}$  is W-equisingular (or just equisingular) if  $\mathcal{X}$  has a stratification in which adjacent pair of strata satisfy condition W, and the parameter space Y is a stratum.

- Example The family of n moving distinct lines is W-equisingular because the pair (X<sub>0</sub>, Y) satisfies W, since X is made up of n smooth surfaces, intersecting along Y, and Y is a submanifold of each smooth surface.
- Since each component of  $\mathcal{X}_0$  satisfies W over Y, so does  $\mathcal{X}_0$ .
- ► Teissier ('81) showed that Verdier's condition W was equivalent to the Whitney conditions over C. (So, whenever you hear Whitney conditions, you can think W.)

## W as an Analytic Inequality

Set-up: We use the basic set-up with X<sup>k+n</sup> a family of hypersurfaces in Y<sup>k</sup> × C<sup>n+1</sup>.

### Proposition

Condition W holds for  $(\mathcal{X}_0, Y)$  at (0,0) if and only if there exists U a neighborhood of (0,0) in  $\mathcal{X}$  and C > 0 such that

$$\|rac{\partial F}{\partial y_l}(y,z)\| \leq C \sup_{i,j} \|z_i rac{\partial F}{\partial z_j}(y,z)\|$$

for all  $(y, z) \in U$  and for  $1 \le l \le k$ .

- Proof: Set A = Y, and calculate the distance between Y and a tangent plane to X<sub>0</sub> at (y, z) which is our B.
- Use DF(y,z)/||DF(y,z)|| for u ∈ B<sup>⊥</sup>, standard basis for the vectors from A.
- ► distance formula says that condition W holds if and only if

## Proof continued

$$\sup_{1 \le l \le k} \frac{\left\|\frac{\partial F}{\partial y_l}(y, z)\right\|}{\left\|DF(y, z)\right\|} \le C'' \operatorname{dist}((y, z), Y) = C' \sup_{1 \le i \le n+1} \left\|z_i\right\|$$

This is equivalent to

$$\left\|\frac{\partial F}{\partial y_{l}}(y,z)\right\| \leq C \sup_{1 \leq i \leq n+1} \left\|z_{i}\right\| \sup_{1 \leq j \leq n+1} \left\|\frac{\partial F}{\partial z_{j}}(y,z)\right\|$$

- Which gives the result.
- ▶ Denote the ideal generated by the partial derivatives of F with respect to the z variables by J<sub>z</sub>(F), and the ideal generated by z<sub>j</sub> by m<sub>Y</sub>. Then z<sub>i</sub> ∂F/∂z<sub>i</sub> are a set of generators for m<sub>Y</sub> J<sub>z</sub>(F).
- The inequality above says that the partial derivatives of F with respect to y<sub>l</sub> go to zero as fast as the ideal m<sub>Y</sub> J<sub>z</sub>(F) does.

# III The Theory of Integral Closure of Ideals and Modules

- We want to describe algebraically what it means for a function to go to zero as fast as an ideal does.
- f is integrally dependent on an ideal l if one of the following equivalent conditions obtain:
- (i) There exists a positive integer k and elements a<sub>j</sub> in I<sup>j</sup>, so that f satisfies the relation f<sup>k</sup> + a<sub>1</sub>f<sup>k-1</sup> + ··· + a<sub>k-1</sub>f + a<sub>k</sub> = 0 in O<sub>X,0</sub>.
- (iii) For all analytic path germs φ : (C, 0) → (X, 0) the pull-back φ\*f = f ∘ φ is contained in the ideal generated by φ\*(I) in the local ring of C at 0. If for all paths φ\*f is contained in φ\*(I)m<sub>1</sub>, then we say f is strictly dependent on I and write f ∈ I<sup>†</sup>, where the part of C

## Integral closure of ideals continued

► The set of all elements of O<sub>X,x</sub> which are integrally dependent on I is the *integral closure of I* and is denoted *I*.

Proposition

- If I is an ideal in  $\mathcal{O}_{X,x}$ , then so is  $\overline{I}$ .
  - Proof: We use property iii). Let φ : (ℂ, 0) → (X, 0) be any analytic curve, g ∈ O<sub>X,x</sub>, f<sub>1</sub>, f<sub>2</sub> in Ī.
  - Then (gf<sub>1</sub> + f<sub>2</sub>) ∘ φ = (g ∘ φ)(f<sub>1</sub> ∘ φ) + (f<sub>2</sub> ∘ φ) ∈ φ<sup>\*</sup>(I), since φ<sup>\*</sup>(I) is an ideal in O<sub>1</sub>.

#### Example

Let  $A = \mathcal{O}_2$ ,  $I = (x^n, y^n)$ . Suppose  $f = x^i y^j$ ,  $i + j \ge n$ . Consider the monic polynomial  $h(T) = T^n - (x^n)^i (y^n)^j$ . Since  $(x^n)^i (y^n)^j$  is in  $(I^i)(I^j) \subset I^{i+j} \subset I^n$ , and h(f) = 0, then  $f \in \overline{I}$ , and  $\overline{I} \supset m_2^n$ .

## Hypersurfaces, W and Integral Closure

#### Proposition

Condition W holds for  $(\mathcal{X}_0, Y)$  at (0, 0) if and only if  $\frac{\partial F}{\partial y_l} \in \overline{m_Y J_z(F)}$  for  $1 \leq l \leq k$ .

Proof: W holds if and only if

$$\|rac{\partial F}{\partial y_l}(y,z)\| \leq C \sup_{i,j} \|z_i rac{\partial F}{\partial z_j}(y,z)\|$$

- ▶ By property 2 this is equivalent to  $\frac{\partial F}{\partial y_l} \in \overline{m_Y J_z(F)}$  for  $1 \le l \le k$ .
- ▶ **Problem** Show that the family of hypersurfaces in  $\mathbb{C}^3$  defined by  $F = x^n + y^n + th, h \in m_2^{n+1}$  is W equisingular.
- What about higher codimension sets?

# The Theory of Integral Closure for Modules: Motivation

Verdier's condition W is based on the distance between the tangent space TX<sub>x</sub> to X at smooth points x and the tangent space T to Y.
 Recall

dist
$$(T, TX_x)$$
 =  $\sup_{\substack{u \in TX_x^{\perp} - \{0\}\\v \in T - \{0\}}} \frac{\|(u, v)\|}{\|u\| \|v\|}.$ 

- If u ∈ TX<sub>x</sub><sup>⊥</sup> {0}, then the set of points perpendicular to u consists of a hyperplane which contains TX<sub>x</sub>. These hyperplanes are called *tangent hyperplanes*; denote a tangent hyperplane to X, x by H<sub>x</sub>, and the collection of all tangent hyperplanes to X, x by C(X)<sub>x</sub>.
- the distance formula becomes:

$$\operatorname{dist}(T, TX_x) = \sup_{H_x \in C(X)_x} \operatorname{dist}(T, H_x)$$

## The Jacobian Module and Tangent Hyperplanes

- If X = F<sup>-1</sup>(0) where F: C<sup>n</sup> → C<sup>p</sup>, F = (f<sub>1</sub>,..., f<sub>p</sub>) then at a smooth point x of X, the entries of Df<sub>i</sub>(x) are the coordinates of linear form defining a tangent hyperplane.
- So, the projectivisation of the rowspace of the matrix of partial derivatives of F is C(X)<sub>p</sub>.
- Since the tangent hyperplanes control the distance between the tangent space of X, p and TY, 0, this suggests looking at the module generated by the partial derivatives of F denoted JM(X), just as we looked at J(F) in the hypersurface case.
- What does  $\overline{JM(X)}$  mean?

# Basic Results from the Theory of Integral Closure for Modules

- Notation: M ⊂ N ⊂ F<sup>p</sup>, F<sup>p</sup> a free O<sub>X,x</sub> module of rank p, M, N submodules of F.
- If *M* is generated by *g* generators {*m<sub>i</sub>*}, then let [*M*] be the matrix of generators whose columns are the {*m<sub>i</sub>*}.

## Definition

If  $h \in F^p$  then h is integrally dependent on M, if for all curves  $\phi$ ,  $h \circ \phi \in \phi^*(M)$ . The integral closure of M denoted  $\overline{M}$  consists of all h integrally dependent on M.

• **Problem**  $\overline{M}$  is a module,  $\overline{\overline{M}} = \overline{M}$ .

• **Example** Let 
$$[M] = \begin{bmatrix} x & y & 0 \\ 0 & x & y \end{bmatrix}$$
, then  $\overline{M} = m_2 \mathcal{O}_2^2$ .

## Module Analogue of Property 2 for Ideals

#### Proposition

(Gaffney-1992, Prop 1.11) Suppose  $h \in \mathcal{O}_{X,x}^p$ , M a submodule of  $\mathcal{O}_{X,x}^p$  of generic rank k on each component of X. Then  $h \in \overline{M}$  if and only if for each choice of generators  $\{s_i\}$  of M, there exists a constant C > 0 and a neighborhood U of x such that for all  $\psi \in \Gamma(Hom(\mathbb{C}^p, \mathbb{C}))$ ,

$$\|\psi(z)\cdot h(z)\| \leq C \sup_{i} \|\psi(z)\cdot s_{i}(z)\|$$

for all  $z \in U$ .

- (ψ(z) ⋅ s<sub>1</sub>(z),...ψ(z) ⋅ s<sub>n</sub>(z)) is a linear combination of the rows of a matrix of generators of M.
- ► So the property is comparing the size of row vectors of *M* with the corresponding element of *h*
- ► The constant C and the neighborhood U depend on h and M but not on ψ.

### Module Analogue of Property 2 for Ideals

#### Corollary

Suppose  $h \in \mathcal{O}_{X,x}^p$ , M a submodule of  $\mathcal{O}_{X,x}^p$  of generic rank k on each component of X. Then  $h \in \overline{M}$  if and only if for each choice of generators  $\{s_i\}$  of M, there exists a constant C > 0 and a neighborhood U of x such that for all  $T \in \mathbb{C}^p$ ,

$$\|T \cdot h(z)\| \leq C \sup_{i} \|T \cdot s_{i}(z)\|$$

for all  $z \in U$ .

Proof: Assume

$$\|\psi(z)\cdot h(z)\|\leq C\sup_{i}\|\psi(z)\cdot s_{i}(z)\|$$

for all  $z \in U$ , then take  $\psi$  to be the constant T; conversely, we can replace T by  $\psi$ , using the fact that the constant C is independent of the choice of T.

## IV Analytic spaces, W and Integral Closure

Set-up: We use the basic set-up with X<sup>k+n</sup> an equidimensional family of equidimensional sets, X<sup>k+n</sup> ⊂ Y<sup>k</sup> × C<sup>N</sup>, JM(X) ⊂ O<sup>p</sup>.

#### Theorem

Condition W holds for  $(\mathcal{X}_0, Y)$  at (0, 0) if and only if  $\frac{\partial F}{\partial y_l} \in \overline{m_Y JM(F)}$  for  $1 \leq l \leq k$ .

- Proof: We re-work the form of Verdier's condition W to fit our current framework. If we work at a smooth point x of X, then a conormal vector u of X at x can always be written as S · DF(x), where S ∈ C<sup>p</sup>; S is not unique unless DF(x) has rank p.
- Conversely, any such S gives a conormal vector. It is clear also that W holds if the distance inequality holds for the standard basis for the tangent space T of Y. Then

## proof continued I

dist
$$(T, TX_x)$$
 =  $\sup_{\substack{u \in TX_x^{\perp} - \{0\}\\v \in T - \{0\}}} \frac{\|(u, v)\|}{\|u\| \|v\|}.$ 

becomes

 $\operatorname{dist}(T, TX_{x}) = \sup_{\substack{S \in \mathbb{C}^{p} - \{0\}\\1 \leq i \leq k, S \cdot DF(x) \neq 0}} \frac{\|S \cdot \frac{\partial f}{\partial y_{i}}\|}{\|S \cdot DF(x)\|}$ because  $\|u\| = \|S \cdot DF(x)\|$ , and  $\|v\| = 1$ .

## proof continued II

So Verdier's condition W becomes:

$$\sup_{\substack{S \in \mathbb{C}^p \\ L \leq i \leq k}} \|S \cdot \frac{\partial f}{\partial y_i}\| \leq C \|z\| \|S \cdot DF(x)\|.$$

Since the functions are analytic and the inequality holds on a Z-open set of X, we can assume it holds on a neighborhood of the origin.
 consider the integral closure condition, ∂F/∂y<sub>i</sub> ∈ m<sub>Y</sub>JM(F) for

 $1 \le l \le k$ . Using the last corollary, we have  $\frac{\partial F}{\partial y_l} \in \overline{m_Y JM(F)}$  for  $1 \le l \le k$  if and only if

$$\sup_{\substack{S \in \mathbb{C}^p \\ 1 \leq i \leq k}} \|S \cdot \frac{\partial f}{\partial y_i}\| \leq C \sup_{1 \leq i \leq n} \|z_i S \cdot DF(x)\|.$$

But this is easily seen to be equivalent to the previous inequality which finishes the proof.

## JM(F) vs. $JM_z(F)$

• Let  $JM_Y(F)$  denote the submodule of JM(F) generated by  $\frac{\partial F}{\partial y_l}, 1 \leq l \leq k, JM_z(F)$  the partials with respect to z.

Proposition

 $JM_Y(F) \subset \overline{m_Y JM(F)}$  if and only if  $JM_Y(F) \subset \overline{m_Y JM_z(F)}$ .

- ▶ Proof: Clear that  $JM_Y(F) \subset \overline{m_Y JM_z(F)}$  implies  $JM_Y(F) \subset \overline{m_Y JM(F)}$ .
- Let  $\phi$  be any curve on  $\mathcal{X}, 0$ . Then

$$\phi^*(JM_z(F)) \subset \phi^*JM(F) = \phi^*JM_z(F) + \phi^*JM_Y(F)$$
$$= \phi^*JM_z(F) + m_1\phi^*JM(F).$$

- Then by Nakayama's lemma, φ<sup>\*</sup>(JM<sub>z</sub>(F)) = φ<sup>\*</sup>JM(F) and φ<sup>\*</sup>(m<sub>Y</sub>JM<sub>z</sub>(F)) = φ<sup>\*</sup>(m<sub>Y</sub>JM(F)).
- Since  $\phi$  is arbitrary,  $\overline{m_Y JM_z(F)} = \overline{m_Y JM(F)}$ .

## Families of ICIS

- ► For W, we compare the size of row vectors of DF(x), with the part of the row vector coming from D<sub>Y</sub>F(x). Since the part coming from D<sub>Y</sub>F(x) must go to zero faster than the whole vector, it is sensible that it suffices to compare it with the part coming from D<sub>z</sub>F. The last proposition justifies this intuition.
- ► Given a family of ICIS in Y<sup>k</sup> × C<sup>n</sup>, JM<sub>z</sub>(F)|X(y) = JM(X<sup>d</sup><sub>y</sub>) and this has finite colength in O<sup>n-d</sup><sub>Xy</sub>, so e(JM(X<sup>d</sup><sub>y</sub>, O<sup>n-d</sup><sub>Xy</sub>, 0) multiplicity of JM(X<sup>d</sup><sub>y</sub>) in O<sup>n-d</sup><sub>Xy</sub> is well defined.
- In the next sections we will see how the multiplicity can be used to give necessary and sufficient conditions for W to hold for a family of ICIS.
- Questions?

## Lecture 4: Equisingularity and ICIS Part 2

by Terence Gaffney



## V Multiplicities of Ideals and Modules

- The multiplicity of an ideal or module or pair of modules is one of the most important invariants we can associate to an *m*-primary module.
- It is intimately connected with integral closure.
- It has both a length theoretic definition and intersection theoretic definition.
- In the applications it has both an infinitesimal and topological/ geometric interpretation.

## Basic Constructions for ideals and modules

- Given a submodule M of a free  $\mathcal{O}_{X^d}$  module F of rank p, we can associate a subalgebra  $\mathcal{R}(M)$  of the symmetric  $\mathcal{O}_{X^d}$  algebra on p generators called the Rees algebra of M.
- If (m<sub>1</sub>,...,m<sub>p</sub>) is an element of M then ∑ m<sub>i</sub>T<sub>i</sub> is the corresponding element of R(M).
- $\mathcal{M}_n$  is the terms of  $\mathcal{R}(M)$  of degree n.
- Projan(R(M)), the projective analytic spectrum of R(M) is the closure of the projectivised row spaces of M at points where the rank of a matrix of generators of M is maximal.
- Projan(R(JM(X))) is the conormal space of X. It consists of the tangent hyperplanes to X<sub>0</sub> and the closure of this space in X × P<sup>n-1</sup>, X ⊂ C<sup>n</sup>.
- Denote the projection to  $X^d$  by c, or by  $c_M$  where there is ambiguity.

## Length Theoretic Definition of Multiplicity

• Denote the length of a module M by I(M).

## Theorem/Definition

(Buchsbaum-Rim-1963) Suppose  $M \subset F$ , M, F both A-modules, F free of rank p, A a Noetherian local ring of dimension d, F/M of finite length,  $\mathcal{F} = A[T_1, \ldots, T_p]$ ,  $\mathcal{R}(M) \subset \mathcal{F}$ , then  $\lambda(n) = l(\mathcal{F}_n/\mathcal{M}_n)$  is eventually a polynomial P(M, F) of degree d+p-1. Writing the leading coefficient of P(M, F) as e(M)/(d + p - 1)!, then we define e(M) as the multiplicity of M.

- **Example** Claim: Let  $M = I = (x^2, xy, y^2) \subset \mathcal{O}_2$ . Then e(M) = 4.
  - We have p = 1, F = O<sub>2</sub>, and we work with F = O<sub>2</sub>[T<sub>1</sub>]. (Notice that ProjanF = C<sup>2</sup>.)

• Now 
$$\mathcal{M}_n = I^n T^n = m_2^{2n} T^n$$
, so

$$I(\mathcal{F}_n/\mathcal{M}_n) = I(\mathcal{O}_2/m^{2n}) = (2n)(2n+1)/2 = 4n^2/2! + (1.o.t.)$$
  
So  $e(M) = 4$ .

## Geometric meaning of multiplicity

- ▶ Suppose  $I = (f_1, ..., f_d) \subset \mathcal{O}_{X^d}$ , then  $e(I) = \deg f$ , where  $f = (f_1, ..., f_d) \colon X^d \to \mathbb{C}^d$ .
- Suppose *I* has more than *d* generators; find  $J = (f_1, \ldots, f_d) \subset I$  and  $\overline{J} = \overline{I}$ , then  $e(I) = \deg f$ , where  $f = (f_1, \ldots, f_d) \colon X^d \to \mathbb{C}^d$ .
- ► J is called a *reduction* of I.
- Suppose M ⊂ O<sup>p</sup><sub>X<sup>d</sup></sub> has d + p − 1 generators. Then e(M, 0) = number of times we count 0 as a point where the rank of M < p. If M has more than d + p − 1 generators, take a reduction with d + p − 1 generators as before.</p>

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## Example

- **Example** Let  $[M] = \begin{bmatrix} x & y & 0 \\ 0 & x & y \end{bmatrix}$ . e(M) = 3, M has 2+2-1=3 generators.
- Let  $[M(t)] = \begin{bmatrix} x t & y t & 0 \\ 0 & x & y \end{bmatrix}$
- Then for  $t \neq 0$ , [M(t)] has rank 1 only at (0,0), (t,0), (t,t).
- So for *M* we should count (0,0) three times when counting the number of points where the rank of *M* < 2, and *e*(*M*) does this.
- For a p × (d + p − 1) matrix, the expected codimension of the set of points where the matrix has less than maximal rank is d.
- This explains why we use d + p 1 generators for the reduction.

## Reductions of Modules

- Goal: Be able to show  $\overline{m_Y J M_z(F)} = \overline{J M_Y(F) + m_Y J M(F)}$
- Given  $M \subset F^p$ , R a submodule of M with  $\overline{M} = \overline{R}$ . Then R is called a *reduction* of M.
- If M ⊂ N ⊂ F<sup>p</sup> or h is a section of N, then h and M generate ideals on ProjanR(N). Denote them by ρ(h) and M.
- If  $h = \sum g_i n_i$ ,  $\{n_i\}$  a set of generators of N then in the chart in which  $T_1 \neq 0$ , we have:
- $\rho(h) = \sum g_i T_i / T_1.$

#### Example

If M is the Jacobian module of X and  $N = F^p$  then  $V(\mathcal{M})$  consists of pairs (x, L) where  $x \in X$  and  $L \in \mathbb{P}Hom(\mathbb{C}^p, \mathbb{C})$ , and  $L \circ DF(x) = 0$ . If H is the hyperplane which is the kernel of L, then the image of DF(x) lies in H.

Looking at (M, N) allows us to "strip out" one copy of N from M, as the following example shows.

### Reductions II

#### Example

Let  $M = I = (x^2, xy, z) = J(z^2 - x^2y)$  and N = J = (x, z). M is the Jacobian ideal of the Whitney umbrella, and N defines the singular locus of the umbrella.

- ▶ working on  $\mathbb{C}^3$ ,  $\mathcal{R}(N) = \mathcal{O}_3[xS, zS]$  is isomorphic to  $R = \mathcal{O}_3[T_1, T_2]/(zT_1 xT_2)$ , by  $xS \to T_1$ ,  $zS \to T_2$ .
- This shows  $B_J(\mathbb{C}^3) = \operatorname{Projan} \mathcal{R}(N)$ .
- Since x<sup>2</sup> = x ⋅ x, xy = y ⋅ x, z = z the map from R(I) to R has image (xT<sub>1</sub>, yT<sub>1</sub>, T<sub>2</sub>):
- ► this induces the ideal sheaf I on ProjanR(N), which is supported only at the point (0, [1, 0]).

## Reductions III

## Proposition

Suppose  $M \subset N \subset \mathcal{O}_{X,0}^p$  are  $\mathcal{O}_X^p$  modules with matrix of generators [M], [N], and [F] is a matrix such that [M] = [N][F]. Let  $\mathcal{F}$  be the ideal sheaf induced on  $\operatorname{Projan}(\mathcal{R}(N))$  by the module F with matrix of generators [F]. Then  $\overline{M} = \overline{N}$  if and only if  $V(\mathcal{F})$  is empty.

- Cf the notes in the section "Blowing up modules and Connection with Ideals II".
- **Problem** Find [F] if  $M = (x^2, y^2)$ ,  $N = (x^2, y^2, xy)$ , and show V(F) is empty.
- M ⊂ N, F as above, then the inclusion i: M → N induces a map π<sub>M</sub> from Projan(R(N)) \ V(F) to Projan(R(M)).
- π<sub>M</sub>(x, p) = (x, F(p)), where F(p) is evaluation at p of the set of generators of F which come from the columns of [F].

## Reductions IV

### Corollary

Suppose M and N as above, then the following are equivalent:

- 1. M is reduction of N.
- 2.  $V(\mathcal{F})$  is empty.
- 3. The induced map  $\pi_M$  is a finite map from  $\operatorname{Projan}(\mathcal{R}(N))$  to  $\operatorname{Projan}(\mathcal{R}(M))$ .

## Proposition

Suppose  $N \subset F$ , F a free  $\mathcal{O}_{X,x}$  module, and suppose the fiber of  $\operatorname{Projan}\mathcal{R}(N)$  over x has dimension k. Then N has a reduction M, where M is generated by k + 1 elements.

- ▶ **Proof:**  $\operatorname{Projan} \mathcal{R}(N) \subset X \times \mathbb{P}^{g-1}$
- Choose plane P in P<sup>g−1</sup> of codimension k + 1 so the intersection of P and the fiber of Projan R(N) over x is empty.

# Proof of the Proposition continued

- Choose coordinates on  $\mathbb{P}^{g-1}$  so P given by  $T_1 = \cdots = T_{k+1} = 0$
- Choosing coordinates on P<sup>g-1</sup> is equivalent to choosing generators on N.
- Let *M* be the submodule of *N* generated by the first *k* + 1 generators of *N* after the new choice of generators. Then the projection onto the first *k* + 1 coordinates of P<sup>g-1</sup>, when restricted to Projan*R*(*N*) gives a finite map to Projan*R*(*M*). Hence *M* is a reduction of *N* by 3).

## Corollary

Suppose  $N \subset F$ , F a free  $\mathcal{O}_{X,x}$  module,  $X^d$  equidimensional, N has generic rank e on each component of X, x, then N has a reduction with d + e - 1 generators.

- ▶ **Proof:** Generic rank of N is e, so the generic fiber dimension of  $\operatorname{Projan}\mathcal{R}(N)$  is e-1, and  $\dim\operatorname{Projan}\mathcal{R}(N) = d + e 1$ .
- ► Then d + e 2 is the largest the dimension of the fiber of ProjanR(N) over x can be, so N has a reduction with (d + e - 2) + 1 generators.

### Exercises

Problem Let JM(X,0)<sub>H</sub> denote the submodule of JM(X) generated by {DF(V)}, V ∈ H. Show that if H is a hyperplane, then JM(X,0)<sub>H</sub> is a reduction of JM(X,0) iff H is not a limiting tangent hyperplane of X at 0. (Hint: Show V(F) is empty.)

# Reductions, multiplicity and Cohen-Macauley Rings

#### Theorem

(Rees) Suppose  $M \subset N$  are m primary submodules of  $F^p$ , and  $\overline{M} = \overline{N}$ . Then e(M) = e(N). Suppose further that  $\mathcal{O}_{X,x}$  is equidimensional, then e(M) = e(N) implies  $\overline{M} = \overline{N}$ .

- Proof:Kleiman-Thorup-1994.
- ▶ **Remark:** If  $\mathcal{O}_{X^{d},x}$  is Cohen-Macaulay, and  $M \subset F^{p}$  has d + p 1 generators, then
- ► e(M) = colength M = colength J(M), the ideal of maximal minors of M. (Buchsbaum-Rim-1963, 2.4 p.207, 4.3 and 4.5 p.223.)

#### Proposition

Let  $X^1, 0 \subset \mathbb{C}^n, 0$  be an ICIS, defined by  $f = (f_1, \ldots, f_{n-1})$ , where  $f_i$  is homogeneous of degree  $d_i$ . Then

$$e(JM(X)) = \left(\sum_{i=1}^{n-1} (d_i - 1)\right) \left(\prod_{i=1}^{n-1} d_i\right).$$

# Multiplicity and Lines in Space

- **Proof:** X consists of  $(\prod_{i=1}^{n-1} d_i)$  lines, by Bezout's theorem.
- ► Choose n 1 columns of the matrix of partial derivatives, such that the submatrix, [N] gotten has rank n - 1 on X except at 0. Denote the module the columns generate by N.
- Can assume N is a reduction of JM(X).
- det[N] is homogeneous of degree (∑<sup>n-1</sup><sub>i=1</sub>(d<sub>i</sub> − 1)), and e(N) =colength of det[N] in O<sub>X</sub>, by Buchsbaum-Rim.
- ► colength of det[N] in O<sub>X</sub> = degree of det[N] as a map from X to C, since O<sub>X</sub> is Cohen-Macauley.
- degree of det[N] on each line in X is the homogeneous degree of det[N]
- ▶ degree of *det*[*N*] on *X* is the sum of the degrees on each component.
- SO

$$e(JM(X)) = e(N) = \left(\sum_{i=1}^{n-1} (d_i - 1)\right) \left(\prod_{i=1}^{n-1} d_i\right)$$

# e(JM(X)) and the Lê-Greuel Theorem

Proposition

(Module form of the Lê-Greuel formula) Let  $X^d$ , 0 be an ICIS, d > 0, H a hyperplane which is not a limit tangent hyperplane to X at the origin. Then

$$e(JM(X),0) = \mu(X) + \mu(X \cap H).$$

Recall, Lê-74 and Greuel-75 proved the following formula:

$$\mu(X) + \mu(X') = \dim_{\mathbb{C}} \frac{\mathcal{O}_{\mathbb{C}^n,0}}{I},$$

where X is the ICIS defined by  $F: (\mathbb{C}^n, 0) \to (\mathbb{C}^k, 0)$ ; F the map with components  $f_1, \ldots, f_k$  and X' the ICIS defined by  $F': (\mathbb{C}^n, 0) \to (\mathbb{C}^{k+1}, 0)$ ; F' the map with components  $f_1, \ldots, f_{k+1}$ , and I is the ideal generated by  $f_1, \ldots, f_k$ , and the  $k + 1 \times k + 1$ -minors  $\frac{\partial(f_1, \ldots, f_{k+1})}{\partial(x_{i_1}, \ldots, x_{i_{k+1}})}$ .

## Lê-Greuel II

#### Proof:

- Let *L* be the linear form defining *H*. Let *L* be  $f_{k+1}$  in the formula.
- The right hand side of the formula becomes  $\mu(X) + \mu(X \cap H)$ .
- ► e(JM(X)<sub>H</sub>) = e(JM(X)) since H is a hyperplane which is not a limit tangent hyperplane to X at the origin.
- ► the ideal of k + 1 × k + 1 minors of a matrix of generators of JM(X ∩ H) is the same as the ideal of k × k minors of a matrix of generators of JM(X)<sub>H</sub>.
- This implies that the colength of I in the formula is the colength of k × k minors of JM(X)<sub>H</sub>, which by the Buchsbaum-Rim theorem is e(JM(X)<sub>H</sub>).

## Calculating Milnor Numbers Inductively

## Proposition

Suppose I defines an ICIS X of dimension 0; then  $\mu(X) = e(I, \mathcal{O}_n) - 1$ 

- **Proof:** *I* an ICIS implies  $I = (f_1, \ldots, f_n)$ .
- Then  $e(I) = deg(f_1, \ldots, f_n)$  at 0 as a map f from  $\mathbb{C}^n, 0 \to \mathbb{C}^n, 0$ .
- $\#f^{-1}(p) = e(I)$ , p not a critical value.
- ▶ Fixing one point, as a common point for every 0 sphere, we get a bouquet of (e(1) 1) 0-spheres. So the Milnor number is e(1, O<sub>n</sub>) 1.

## Calculating Milnor Numbers: An Example

## Corollary

Let  $X^1$  be a homogeneous ICIS, then

$$\mu(X) = \left(\sum_{i=1}^{n-1} (d_i - 1)\right) \left(\prod_{i=1}^{n-1} d_i\right) - \prod_{i=1}^{n-1} d_i + 1.$$

• **Proof** 
$$e(JM(X), 0) = \mu(X) + \mu(X \cap H)$$
.

• Solving for  $\mu(X)$  we get

$$\mu(X) = e(JM(X), 0) - \mu(X \cap H).$$

Since X has dimension 1, µ(X ∩ H) = m(X) − 1 by the previous proposition. Since X is a union of lines we know e(JM(X),0) = ∑<sub>i=1</sub><sup>n-1</sup>(d<sub>i</sub> − 1)) ∏<sub>i=1</sub><sup>n-1</sup> d<sub>i</sub>, while m(X) − 1 = (∏<sub>i=1</sub><sup>n-1</sup> d<sub>i</sub>) − 1, from which the result follows.

# Principle of Specialization of Integral Dependence (PSID)

 First proved by Teissier-'73 for ideals, our proof uses ideas which appear in Teissier-'80.

#### Theorem

G-Kleiman '99 (Principle of Specialization of Integral Dependence) Assume that X is equidimensional, and that  $y \mapsto e(y)$  is constant on  $Y^k$ . Let h be a section of a free  $\mathcal{O}_X$  module E whose image in E(y) is integrally dependent on the image of M(y) for all y in a dense Zariski open subset of Y. Then h is integrally dependent on M.

# Equisingularity of families of ICIS: Sufficiency

#### Theorem

Let  $\mathcal{X}$  be a family of ICIS over  $Y^k$  as in the basic setup. Suppose e(mJM(X(y), 0)) is independent of y. Then X - Y is smooth, and the pair (X - Y, Y) satisfies W.

- Proof: Since e(y) is upper semi-continuous, there can be no points on X(y) except the origin in the co-support of mJM(X(y)); hence JM(X(y)) has maximal rank except at 0 so X(y) is smooth except at 0.
- ► This also implies that JM<sub>z</sub>(X) has maximal rank off Y, so X Y is smooth.
- By the genericity of W, we have ∂F/∂y<sub>l</sub> ∈ m<sub>Y</sub>JM(F) for 1 ≤ l ≤ k on a Z-open subset of Y. So by the PSID, we have that it holds at all points and the family is W equisingular.

# Equisingularity of families of ICIS: Necessity

 Given the product mJM(X), there is an expansion formula which relates e(mJM(X)) our infinitesimal invariant to the μ<sub>\*</sub> invariants, which are our topological/geometric invariants.

#### Theorem

Suppose  $X^d$ , 0 is an ICIS,  $H_i$  a generic plane of codimension i for  $X^d$  then

$$e(mJM(X,0)) = \binom{n-1}{d}m(X,0) + \sum_{i=0}^{d-1}\binom{n-1}{i}e(JM(X\cap H_i,0))$$
$$= \binom{n-1}{d}(\mu_d(X,0)+1) + \sum_{i=0}^{d-1}\binom{n-1}{i}(\mu_i(X,0)+\mu_{i+1}(X,0))$$

- ▶ **Proof** (G-'96)
- Corollary
- Let  $\mathcal{X}$  be a family of ICIS over  $Y^k$  as in the basic setup. Suppose e(mJM(X(y), 0)) is independent of y. Then the  $\mu_*$  sequence of X(y) is independent of y.

# Equisingularity of families of ICIS: Necessity II

**Proof:**  $\mu_*(X(y))$  sequence is upper semi-continuous in y, as is e(mJM(X(y), 0)); so, all of the terms in the sum must remain constant, if the value of the sum does.

#### Theorem

(Necessity) Suppose  $\mathcal{X}$  is a family of ICIS, and the pair  $(\mathcal{X} - Y, Y)$  satisfies W at the origin. Then, the  $\mu_*$  sequence of X(y) is independent of y, as is  $e(m_y JM(X(y)))$ .

- Proof: Since the families of generic plane sections also satisfy W by Teissier-'81 (See also the notes for a new proof), it follows that these families are topologically trivial,
- ► Hence the µ<sub>\*</sub> sequence of X(y) is independent of y. This implies e(m<sub>y</sub>JM(X(y))) is independent of y by the expansion formula.